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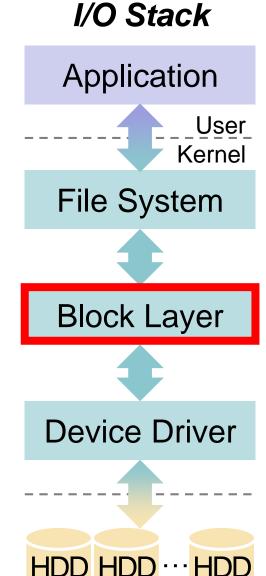
The Chinese University of Hong Kong

CSCI5550 Advanced File and Storage Systems Lecture 02: RAID and Data Integrity

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- Generic Block Layer
- <u>Redundant</u> <u>Arrays of</u> <u>Inexpensive</u> <u>D</u>isk
 - RAID Interface and Internals
 - Fault Model: Fail-Stop
 - RAID Levels and Analysis
 - Capacity, Reliability, and Performance
 - RAID Reconstruction
- Data Integrity
 - Other Disk Failure Modes and Handling
 - Latent Sector Error
 - Corruption
 - Lost Writes
 - Scrubbing

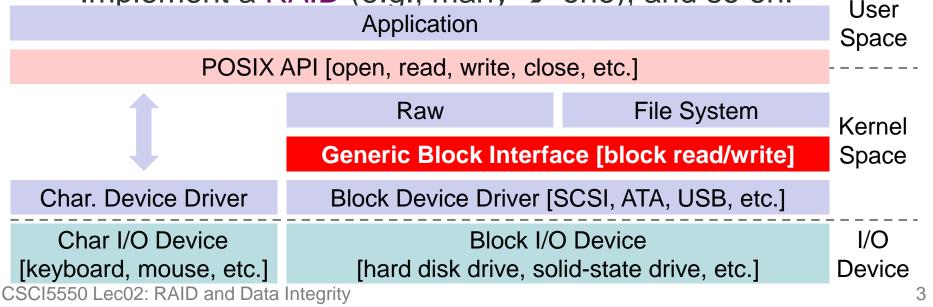




Generic Block Layer



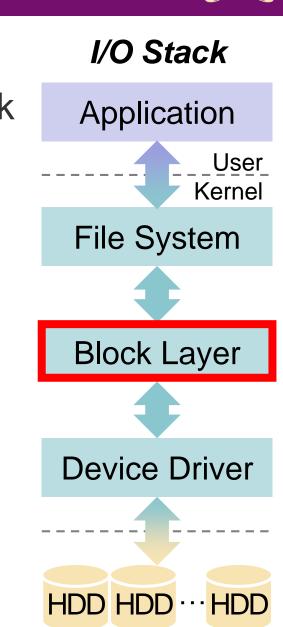
- Generic Block Layer: A kernel component that handles the requests for all block devices in blocks.
- Thanks to this abstraction, the kernel may easily:
 - Schedule I/O requests for I/O devices (e.g., HDD);
 - Implement data buffer to keep data blocks to optimize I/O;
 - Manage logical volumes (e.g., one disk → many volumes);
 - Implement a RAID (e.g., many \rightarrow one), and so on.





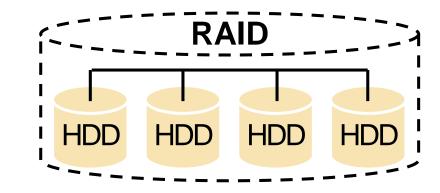


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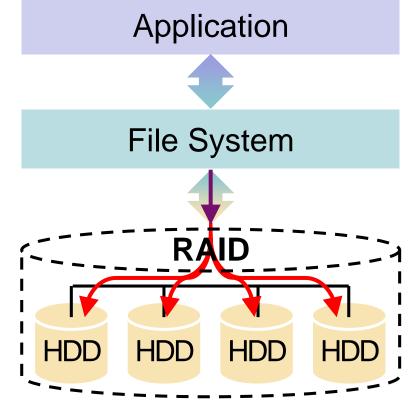
Redundant Arrays of Inexpensive Disks

- RAID: <u>R</u>edundant <u>A</u>rrays of <u>Inexpensive</u> <u>D</u>isks
 - Aggregates multiple physical disks as one logical (and bigger) one.
 - Developed by researchers at Berkeley in late 80s.
- RAID offers the following advantages transparently with the same interface as a single disk.
 - Capacity: more disks
 - Reliability: fault tolerance by maintaining redundancy
 - Performance: parallelism



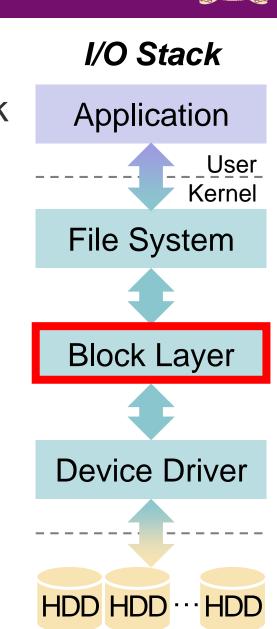
RAID Interface and Internals

- RAID converts a logical I/O from the file system into one or multiple physical I/Os to disks(s).
- RAID is often built as a separate hardware box, with a standard bus to a host.
 - A microcontroller to run firmware for RAID operations.
 - Some memory to buffer data blocks as they are read/written.
 - Specialized logic to perform parity (redundancy) calculation.
- RAID can be also built by software (e.g., mdadm).





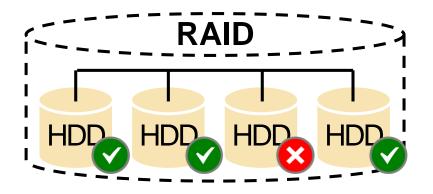
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Fault Model



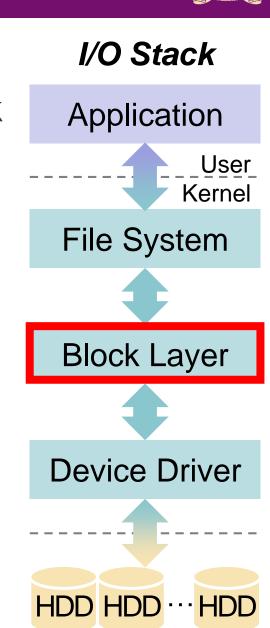
- RAID is designed to detect and recover from certain kinds of disk faults.
- Let's begin with the simplest **fail-stop** fault model:
 - If a disk is working, all its data can be read/written.
 - If a disk fails, all its data are permanently lost.
 - RAID controller can immediately detect if a disk fails.



• In practice, disk failures can be more complex (e.g., bad sectors in a working disk or "silent" failures).



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Basic RAID Levels: A Glance

Disk 0

Disk 1

Disk 2

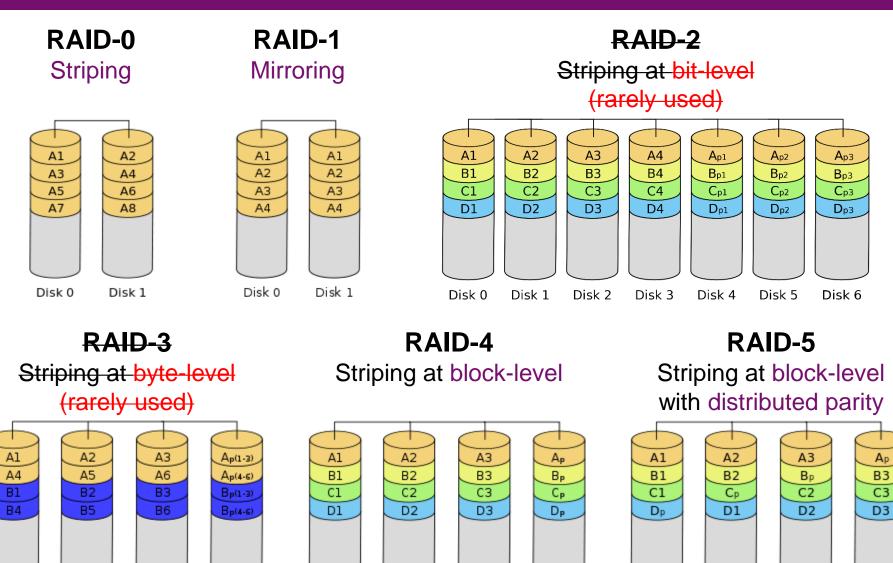
Disk 3

Disk 0

Disk 1

Disk 2





Disk 0 Disk 1 Disk 2 Disk 3 https://en.wikipedia.org/wiki/Standard_RAID_levels

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Disk 3

RAID Analysis: Three Aspects

Capacity

- The effective storage size in number of blocks
 - Let **N** be the total number of disks in RAID.
 - Let **B** be the total number of blocks in a single disk.

Reliability

- The number of tolerable disk failures.

Performance

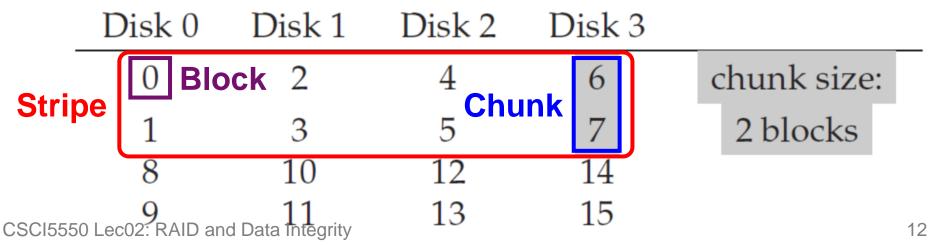
- Single-Request Latency: $T_{I/O} = T_{seek} + T_{rotation} + T_{transfer}$
 - Let **T** be the latency that a request to a single disk would take.
- Steady-State Throughput: $Rate_{I/O} = Size_{Transfer} \div T_{I/O}$
 - Let S and R be the single-disk transfer bandwidths (or rates) under sequential and random workloads, respectively (S >> R).



Terminologies



- Disks organize data in **blocks** (e.g., 4KB).
- RAID usually distributes data across disks in units of chunks, which is composed of one or more blocks.
 - Chunk size mostly affects performance of RAID.
 - Small chunk size increases parallelism of reads/writes.
 - Large chunk size reduces positioning time of disks.
 - Let the chunk size be the block size in our analysis.
- A stripe refers to the same row of chunks.



RAID-0 (Striping)



- RAID-0 distributes data blocks across disks in a round-robin fashion (without any redundancy!).
 - Capacity: <u>N * B</u> (the upper bound)
 - Reliability: <u>0</u> (no fault tolerance)
 - Performance:
 - <u>Read/Write Latency</u>: <u>T</u> (the same as in a single disk)
 - The I/O request is simply redirected to one of the disks.
 - <u>Sequential Read/Write Throughput</u>: <u>N * S</u> (full bandwidth)
 - <u>Random Read/Write Throughput</u>: <u>N * R</u> (full bandwidth)

| | Disk 0 | Disk 1 | Disk 2 | Disk 3 |
|-------------|--------|--------|--------|--------|
| Full Stripe | 0 | 1 | 2 | 3 |
| | 4 | 5 | 6 | 7 |
| | 8 | 9 | 10 | 11 |
| | 12 | 13 | 14 | 15 |

Discussion



 Question: How to do address mapping from a logical block address to a physical block address in RAID?

• Answer:

- Let the chunk size be the block size.
- Let LBA be the logical block address.

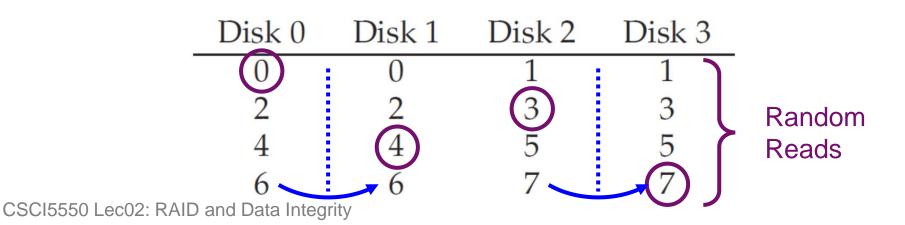
Disk = LBA % number_of_disks Offset = LBA / number_of_disks

• Bonus: What about a general chunk size (i.e., a chunk is of multiple blocks)?

RAID-1 (Mirroring) (1/2)

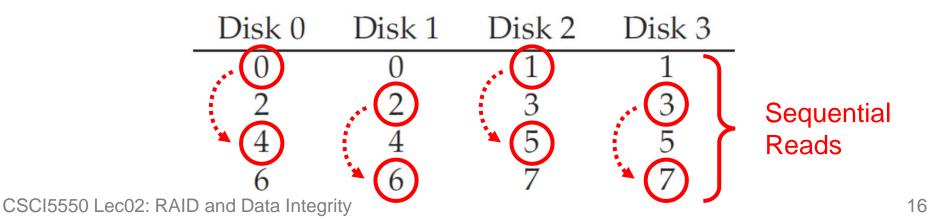
- **RAID-1** keeps **two** physical copies for every block.
 - Capacity: <u>N * B/2</u> (very expensive!)
 - **Reliability**: $\underline{1}$ (any one for certain); $\underline{up \ to \ N/2}$ (if lucky!)
 - Performance:
 - <u>Read/Write Latency</u>: <u>**T**</u> (the same as in a single disk)
 - Read from one hard copy; Write to two hard copies in parallel.
 - Random Write Throughput: N * R/2 (all in use, but half effective)
 - Random Read Throughput: N * R (**possible** to reach full bandwidth)

- E.g., randomly read blocks 0, 3, 4, and 7



RAID-1 (Mirroring) (2/2)

- **RAID-1** keeps **two** physical copies for every block.
 - Capacity: <u>N * B/2</u> (very expensive!)
 - **Reliability**: $\underline{1}$ (any one for certain); $\underline{up \ to \ N/2}$ (if lucky!)
 - Performance (cont'd):
 - Sequential Write Throughput: N * S/2 (all in use, but half effective)
 - Sequential Read Throughput: N * S/2
 - Why not N * S (similar to random read throughput)?
 - Answer: Each disk receive a request for every other block.
 While it is rotating over the skipped block, it is not delivering effective bandwidth.



Discussion



- In RAID-1, updates (i.e., writes) to both copies of each logical block must be consistent (or atomic, i.e., both copies are updated or neither is updated).
- Question: How to guarantee the consistency when a power loss (or system crash) occurs?
- **Answer**: Write-Ahead Log (will be discussed later)
 - Do the log before updating two disks.
 - Use a small amount of non-volatile, battery-backed RAM for better logging performance.
 - Replay the log if a crash occurs.



RAID-4 (1/5)



- **RAID-4** adding redundancy (known as **parity**) to a disk for each stripe.
 - One disk is dedicated as the parity disk.

| Disk 0 | Disk I | Disk 2 | Disk 3 | Disk 4 |
|--------|--------|--------|--------|--------|
| 0 | 1 | 2 | 3 | P0 |
| 4 | 5 | 6 | 7 | P1 |
| 8 | 9 | 10 | 11 | P2 |
| 12 | 13 | 14 | 15 | P3 |

- Parity must withstand the loss of any one block in a stripe.

- Parity can be computed via **bitwise XOR**.
- Recovery? Block0 = Block1 XOR Block2 XOR Block3 XOR Parity

| | Block0 | Block1 | Block2 | Block3 | Parity |
|--------------|-----------------|--------------|--------|--------|--------|
| | 00 | 10 | 11 | 10 | 11 |
| | 10 | 01 | 00 | 01 | 10 |
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RAID-4 (2/5)



- **RAID-4** adding redundancy (known as **parity**) to a disk for each stripe.
 - **Capacity**: N 1 (one dedicated parity disk)
 - **Reliability**: <u>1</u> (any one for certain and no more)
 - Performance:
 - Random Read Throughput: (N 1) * R (parity disk has no effect!)
 - Sequential Read Throughput: (N 1) * S (parity disk has no effect!)

| Disk 0 | Disk 1 | Disk 2 | Disk 3 | Disk 4 |
|--------|--------|--------|--------|--------|
| 0 | 1 | 2 | 3 | P0 |
| 4 | 5 | 6 | 7 | P1 |
| 8 | 9 | 10 | 11 | P2 |
| 12 | 13 | 14 | 15 | P3 |

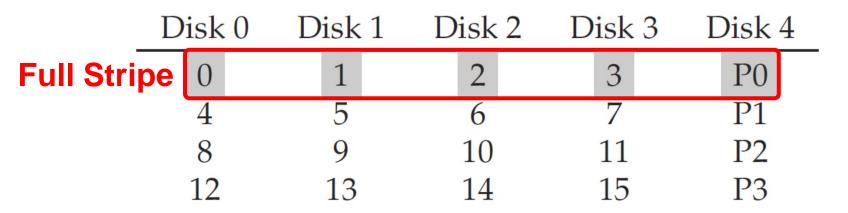
RAID-4 (3/5)



RAID-4 adding redundancy (known as parity) to a disk for each stripe.

- Performance:

- Sequential Write Throughput: (N 1) * S (parity disk has no effect!)
- How to do full-stripe write under RAID-4?
 - ① Buffer all data blocks of a stripe
 - ② Compute the parity block
 - ③ Write all data and parity blocks in parallel



RAID-4 (4/5)



• **RAID-4** adding redundancy (known as **parity**) to a disk for each stripe.

- Performance:

- Random writes need to update both data and parity blocks.
 Approach 1) Additive Parity (as known as reconstruct-writes)
 - ① Read all other data blocks in a stripe in parallel
 - ② XOR those with the new block to form a new parity block
 - ③ Write the new data block and new parity block to disks

Approach 2) Subtractive Parity (as known as read-modify-writes)

- ① Read only the old data block to be updated and old parity block
- ② Compute the new parity block: $P_{new} = (D_{new} \wedge D_{old}) \wedge P_{old}$
- ③ Write the new data block and new parity block to disks
- Random Write Throughput: $\frac{R}{2}$ (using subtractive parity)
 - Each random write triggers two reads and two writes.

» The reads can happen in parallel, as can the writes. CSCI5550 Lec02: RAID and Data Integrity

Discussion



- Question: What is the tradeoff between additive parity and subtractive parity?
- Answer: Additive parity incurs more I/Os if the number of disks is large; vice versa for subtractive parity.
- Bonus: What is the cross-over point?
 - That is, how many disks would need so that the additive method performs fewer I/Os than subtractive method.

RAID-4 (5/5)



RAID-4 adding redundancy (known as parity) to a disk for each stripe.

- Performance:

- <u>Read Latency</u>: <u>**T**</u> (the same as in a single disk)
 - A single read is just redirected to a single disk.
- <u>Write Latency</u>: T * 2 (twice in a single disk)
 - A single write needs two reads and two writes (subtractive parity).
 - » The reads can happen in parallel, as can the writes.

| Disk 0 | Disk 1 | Disk 2 | Disk 3 | Disk 4 |
|--------|--------|--------|--------|--------|
| 0 | 1 | 2 | 3 | P0 |
| *4 | 5 | 6 | 7 | +P1 |
| 8 | 9 | 10 | 11 | P2 |
| 12 | *13 | 14 | 15 | +P3 |

RAID-5



- **RAID-5** rotates parity blocks across stripes.
 - Other operations remain the same as RAID-4.

| Disk 0 | Disk 1 | Disk 2 | Disk 3 | Disk 4 |
|--------|--------|--------|--------|--------|
| 0 | 1 | 2 | 3 | PO |
| 5 | 6 | 7 | P1 | 4 |
| 10 | 11 | P2 | 8 | 9 |
| 15 | P3 | 12 | 13 | 14 |
| P4 | 16 | 17 | 18 | 19 |

 Identical to RAID-4 in the following: capacity, reliability, read/write latency, and sequential r/w throughput.

- Random Read Throughput: N * R (**possible** to reach full bandwidth).
- Random Write Throughput: $\frac{N}{4} * R$ (improved greatly over RAID-4).

– Assume a large number of random writes keeps all disks evenly busy.

The factor of four loss: Each RAID-5 write still need four I/O operations.
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RAID Comparison: A Summary

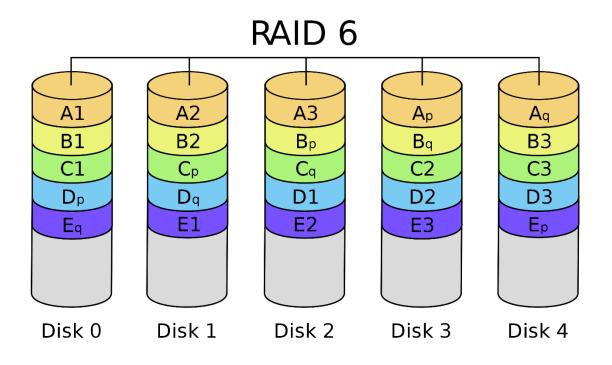


| RAID-0 RA | ID-1 | -1 RAID-4 | | AID-5 |
|--|----------------------------|----------------------------|--|-----------------|
| A1 A3 A5 A7 A6 A8 A1 A2 A1 A2 A3 A4 A4 A3 A4 | A1 A2 A3 A4 D1 | A2 B2 C2 D2 D3 | Ap A1 A2 Bp Cp C1 Cp Dp Dp D1 | Bp B3 C2 C3 |
| | RAID-0 | RAID-1 | RAID-4 | RAID-5 |
| Capacity | $N \cdot B$ | $(N \cdot B)/2$ | $(N-1) \cdot B$ | $(N-1) \cdot B$ |
| Reliability | 0 | 1 (for sure) | 1 | 1 |
| | | $\frac{N}{2}$ (if lucky) | | |
| Throughput | | | | |
| Sequential Read | $N \cdot S$ | $(N/2) \cdot S$ | $(N-1) \cdot S$ | $(N-1) \cdot S$ |
| Sequential Write | $N \cdot S$ | $(N/2) \cdot S$ | $(N-1) \cdot S$ | $(N-1) \cdot S$ |
| Random Read | $N \cdot R$ | $N \cdot R$ | $(N-1) \cdot R$ | $N \cdot R$ |
| Random Write | $N \cdot R$ | $(N/2) \cdot R$ | $\frac{1}{2} \cdot R$ | $\frac{N}{4}R$ |
| Latency | | | | 1 |
| Read | T | T | T | T |
| Write | T | T | 2T | 2T |

Other Basic RAID Levels



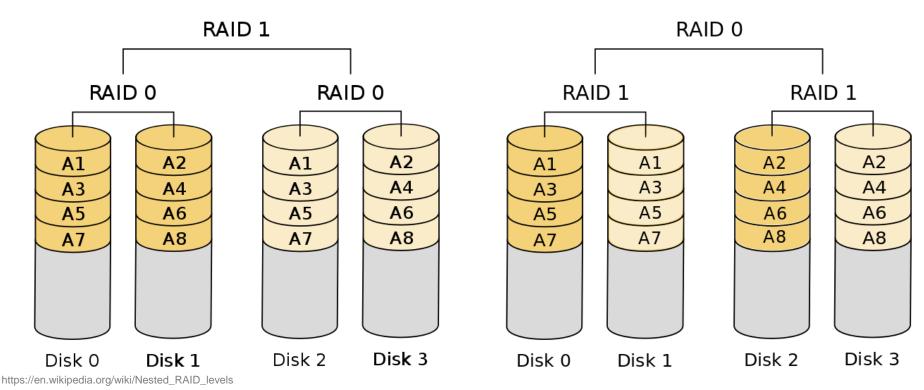
- RAID-6 can tolerate multiple disk faults by
 - Introducing more redundancy (i.e., parity blocks);
 - Using more powerful error correction code (e.g., Reed-Solomon code).



https://en.wikipedia.org/wiki/Standard_RAID_levels

Advanced RAID Levels

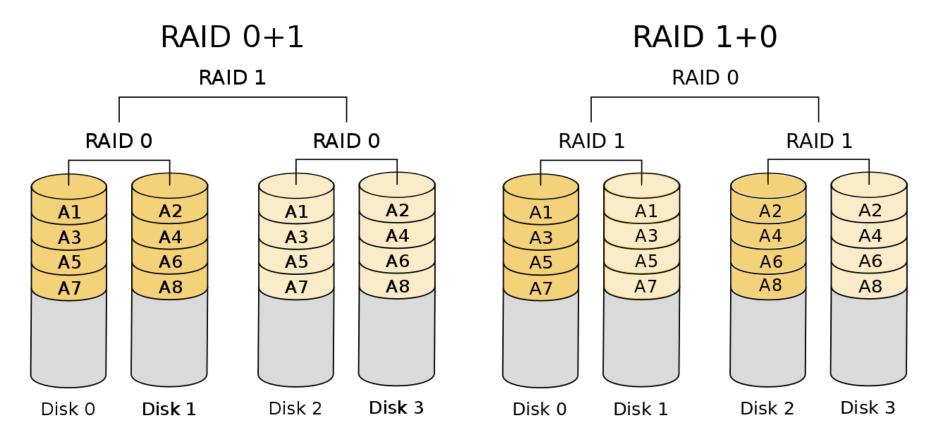
- Nested RAID (or Hybrid RAID): Combines two or more of basic RAID levels (i.e., RAID-0~RAID-6).
 - To gain performance, additional redundancy or both, as a result of combining properties of different RAID layouts.
 RAID 0+1
 RAID 1+0



Discussion



• Question: Which one is better? RAID-01 or RAID-10?

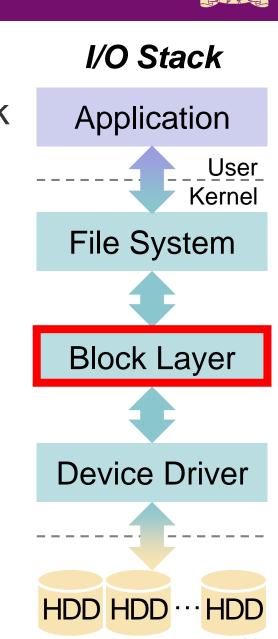


 Answer: The reliability of RAID-10 is better than RAID-01 in more failure scenarios.



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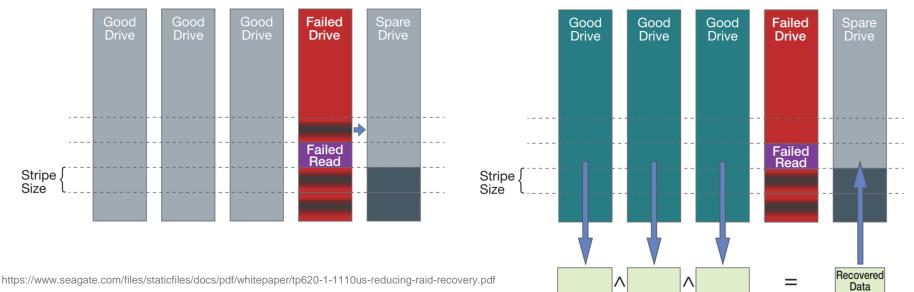
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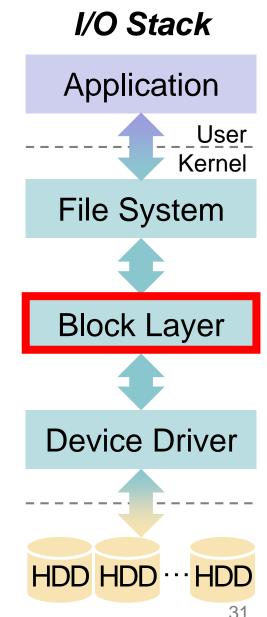
RAID Reconstruction



- The RAID system needs to be **reconstructed** when a disk fails.
 - The failed disk needs to be replaced by a spare one.
 - Hot Spare: enables a RAID system to automatically failover.
 - **Cold Spare**: resides in the RAID but requires manual intervention.
 - The entire spare disk needs to be rebuilt by using either failed disk or other healthy disks in the RAID system.



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Data Integrity and Other Failure Modes

- So far, we only consider the fail-stop fault model.
 Either the entire disk is working, or it fails completely.
- The data integrity should be further ensured.
 - The data put into the system must be the same as returned.
- The fail-partial fault model is more practical.
 - Disks seem working, but some blocks can't be used.
- Two common types of single-block failures.
 - Latent Sector Errors: Blocks are inaccessible or damaged.
 - (Silent) Corruptions: Blocks hold wrong content.

| | Cheap (e.g., SATA) | Costly (e.g., SCIS) |
|----------------------|--------------------|---------------------|
| Latent Sector Errors | 9.40% | 1.40% |
| Corruptions | 0.50% | 0.05% |

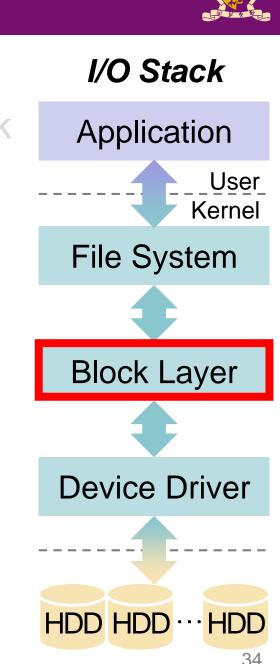
Failure percentages of 1.5 million drives over a 3-year span.

Latent Sector Errors



- LSEs arise when a disk sector (or group of sectors) has been damaged in some way such as:
 - Head crash damages disk surface, making bits unreadable.
 - Cosmic rays flip bits, leading to incorrect contents.
- LSEs can be easily detected when accessing a block.
 - If a block cannot be accessed, the disk returns an error.
 - If a block can be accessed but the in-disk error correcting codes (ECC) cannot fixed LSEs, the disk returns an error.
 - ECCs associate the data with some redundancy for detecting and recovering (usually a fixed number of) error bits.
 - Classical ECCs include Golay, BCH, Hamming codes, etc.
- Most RAID levels (*except RAID-0*) can recover LSEs by leveraging the redundancy.

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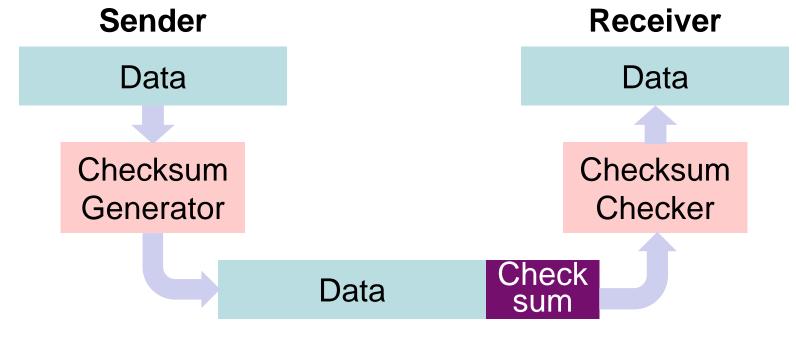
Corruptions



- Corruptions refer to the cases where a block becomes corrupt but not detectable such as:
 - A heathy block may get corrupted when it is transferred between the host and the disk across a faulty bus.
 - Buggy disk firmware writes a block to the wrong location.
 - In such a case, the in-disk ECC indicates the block contents are fine, but the wrong block is returned to users.
- These types of faults are particularly insidious because they are silent faults.
 - The disk itself has no idea when returning the faulty data.
- Once it is known that a particular block is corrupt, recovery is the same as before.
 - We need a way to **detect** corruptions.

Detecting Corruption: The Checksum

- Checksum: ensures data integrity despite corruption.
 - It is simply a small summary of the data contents (e.g., 4-8 bytes), computed from a chunk of data (e.g., 4KB).
 - The corruption can be detected <u>only if</u> the checksum does NOT match the data contents.
 - Why? Beyond the checksum capability or checksum corrupted.



The Simplest Checksum: XOR



- One simple way: exclusive or (XOR).
- Considering a 4-byte checksum over a data block of 16 bytes (lined up in groups of 4 bytes per row):
 - The checksum is computed by XOR'ing over each column.

00110110 01011110 11000100 11001101

10111010 00010100 10001010 10010010

11101100 11101111 00101100 00111010

XOR) 01000000 10111100 11110110 01100110

Checksum 00100000 00011011 10010100 00000011

- **Collision**: Different blocks have the same checksum.
- Limitation: Even number of error bits in a column.
- **Bonus**: Can you do "error correction" with XOR?

Fletcher and CRC Checksum(s)



- Fletcher Checksum: iteratively computes two check bytes, namely s1 and s2, as follows:
 - Assume a block D consists of bytes d1, d2, ..., dn.

 Cyclic Redundancy Check (CRC): divides the data block by an agreed upon value (k) and takes the remainder of this division as the checksum.

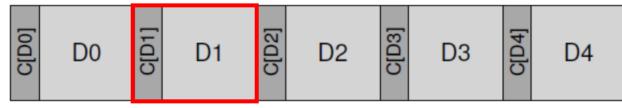
- It is one of the most commonly-used checksums today.

 Both are good at detecting single-bit, double-bit, and even a large portion of burst errors (*think about why*).
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Checksum Layout



- How should checksums be stored on disk?
- Given five data blocks D0, D1, ..., D4, let's call the checksum of Di as C(Di).
- 1) The checksum can be added next to each block:



- Requiring disks be formatted with non-512-byte sector.
- 2) The checksums can be also packed into a block:

| 00 CD3 CD3 D0 | D1 | D2 | D3 | D4 |
|---------------|----|----|----|----|
|---------------|----|----|----|----|

- Working on all disks but less efficient.
 - Two writes for checksum block and the data block.

Misdirected Writes

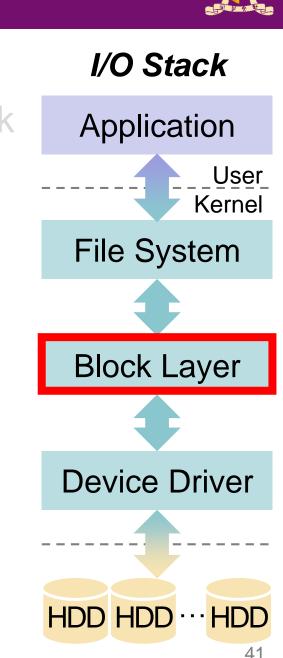


- Recall: A corruption will occur when buggy disk firmware writes a block to the wrong location.
 - This failure mode is called a **misdirected write**.
- Solution: Adding a little more information to checksum.
 - The physical identifier (ID) can be used to verify whether the data chuck resides within a "correct" location.



• Redundancy is always the key for both error detection (in this case) and recovery (in others such as RAID). CSCI5550 Lec02: RAID and Data Integrity 40

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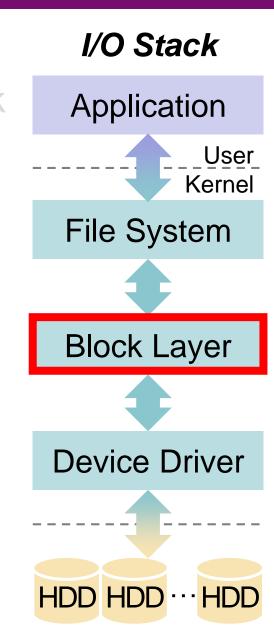
Lost Writes



- Lost Write: The device informs the upper layer that a write has completed but it's not persisted.
 - Basic checksum with physical identity does NOT help.
 - The old block likely has a matching checksum, and the physical ID used above will also be correct.
- Possible Solutions
 - Read-after-Write
 - It may double the I/O.
 - Maintain additional checksum elsewhere in the system
 - It still can't solve the problem if both writes are lost.

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- Generic Block Layer
- <u>Redundant</u> <u>Arrays of Inexpensive</u> <u>Disk</u>
 - RAID Interface and Internals
 - Fault Model: Fail-Stop
 - RAID Levels and Analysis
 - Capacity, Reliability, and Performance
 - RAID Reconstruction
- Data Integrity
 - Other Disk Failure Modes and Handling
 - Latent Sector Error
 - Corruption
 - Lost Writes
 - Scrubbing



Scrubbing



- Unchecked data are problematic for a reliable system.
 - Bit rot could accumulate and eventually become unrecoverable anymore.
- **Disk scrubbing** is a periodic process that:
 - Reads through every block;
 - Checks whether checksums are still valid;
 - Repairs the problem if needed;
 - Scheduled on a nightly or weekly basis.



Summary

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